

Vehicle Parameters for a Jaguar X-Type

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We state parameters for simulating the driving behavior of a Jaguar X-Type:

- Mass: 2200 kg
- Moment of inertia: 3344 Nm²
- Front axle to center of gravity: 1.432 m
- Rear axle to center of gravity: 1.472 m
- Wheel base to center of gravity: 0.4 m
- Half car width: 0.8125 m
- Tire radius: 0.333 m
- Tire spinning inertia: 0.5 N m²
- Load transfer time constant: 0.01 s.

For tire-road interaction we use a Pacejka-type tire model of the form

$$F_l = \frac{\sigma_l}{\bar{\sigma}_l} \cdot \mu D_l \cdot \sin \left(C_l \operatorname{atan} \left(\frac{1}{\mu} B_l (1 - E_l) \kappa_0 + E_l \operatorname{atan} \left(\frac{1}{\mu} B_l \kappa_0 \right) \right) \right)$$

$$F_c = -\frac{\sigma_c}{\bar{\sigma}_c} \cdot \mu D_c \cdot \sin \left(C_c \operatorname{atan} \left(\frac{1}{\mu} B_c (1 - E_c) \alpha_0 + E_c \operatorname{atan} \left(\frac{1}{\mu} B_c \alpha_0 \right) \right) \right)$$

where

$$\sigma_l = \frac{\kappa}{\sqrt{\kappa^2 + (e_d \cdot \tan \alpha)^2}}$$

$$\sigma_c = \frac{e_d \tan \alpha}{\sqrt{\kappa^2 + (e_d \cdot \tan \alpha)^2}}.$$

Inputs to the tire model are the slip angle α , the slip ratio κ , and the road friction factor μ . It holds

$$\kappa^0 = 100 \cdot \frac{\sigma_s \bar{\sigma}_l}{1 + \sigma_s \bar{\sigma}_l}$$

$$\alpha^0 = \operatorname{atan} \left(\frac{1}{1 - \kappa} \sqrt{\kappa^2 + (\tan \alpha)^2} \right),$$

and further

$$e_d = e_{d0} - \frac{e_{d0} - 1}{1 + \sigma_s^{2.5}}$$

$$\sigma_s = \frac{1}{1 - \kappa} \sqrt{\left(\frac{\kappa}{\bar{\sigma}_l} \right)^2 + \left(\frac{\tan \alpha}{\bar{\sigma}_c} \right)^2}.$$

For front and rear tires e_{d0} is given by 1.764 and 1.725, respectively. Under normal load distribution, the remaining tire parameters are

Parameter	<i>front</i>	<i>rear</i>	Parameter	<i>front</i>	<i>rear</i>
$\bar{\sigma}_l$	0.105	0.106	$\bar{\sigma}_c$	0.185	0.182
B_l	0.201	0.200	B_c	0.201	0.174
C_l	1.65	1.65	C_c	1.3	1.3
D_l	5620.199	5484.323	D_c	4868.778	4753.954
E_l	0.613	0.614	E_c	-1.229	-1.177